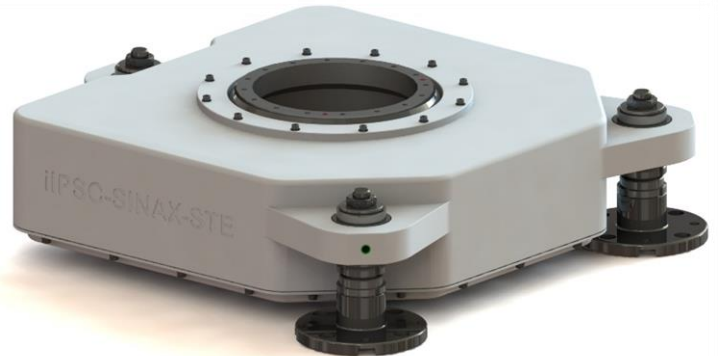


# iIPSC-SINAX

## Single Axis Gyro Stabilized Naval Platform for up to 300 kg Payload

### Key Features

- Surface vehicle based Single-axis gyro stabilized platform for EO/IR imaging, antenna pointing and target tracking with geo-referencing capability
- Light weight system (< 50 kg) to carry a balanced payload up to 300 kg (or customized)
- Integrated direct torque drive for highest resolution, negligible hysteresis and fast dynamics (> 100 °/s, 200 °/s<sup>2</sup>)
- Cable Through for customer payload; as option optical sliprings for signal transmission and gold plated sliprings for power transmission
- Angular freedom unlimited, but can be limited to protect payload cables if any (by HW and SW)
- Available Features:
  - iSCU: Gyro based Stabilization and Control Unit
  - iOET<sup>2</sup>: Video Target Tracker
  - iJP: Joystick Panel for control
  - INS/GNSS: geo-referencing with down to centimeter-level accuracy and for blind-pointing support
  - Video Fusion, Image Blending
- Designed to operate in harsh environment on trucks and on naval vessels.



### Description

Direct drive brushless servo motors combined with high resolution encoders are ensuring the precise and smooth tracking and positioning of the iIPSC-SINAX.

The motion axis is sealed. The selected materials are corrosion resistant and surface treated to withstand harsh land based, airborne or shipboard environmental conditions. Due to its open architecture, the instrument can be equipped e.g. with phased-array antennas (see the picture on the right, where the iIPSC-SINAX, just mounted on iMAR's hexapod 6D motion simulator, carries a large antenna) or any other payload.

iMAR Navigation GmbH, located in Germany, is designer, manufacturer and system integrator of the entire iIPSC-SINAX (mechanics, electronics, gyro stabilization, INS/GNSS data fusion and motion control). Customer specific adaptations can be provided on request.

### Options

- additional elevation axis assembly enabling multi axes stabilization (see also iIPSC-MSG).
- iOET<sup>2</sup> Opto Electronic Target Tracking for Auto Video Tracking (with multi target capability and fast 50 measurements / second).
- dynamic gyro stabilization with integrated INS/GPS positioning including true north referencing and geo-referencing for target localization with sub-decimeter performance (iINAT series).
- optional spring isolated base plate to prevent high frequency environmental disturbance from the instrument.
- transportation container



## Specification Summary

### General Configuration

Payload:	antenna or other devices (customized)
Payload weight, nominal:	up to 300 kg, centered and balanced
Payload Signals:	by direct lines / wrapped cables (slip rings as option)
Power Consumption:	up to 1'000 W, 24 V DC (depends on acceleration) < 50 W at standstill
Platform Weight:	50 kg plus payload

### Performance

Angular freedom (deg)			<b>Azimuth</b> continuous (limited to +/- 90 deg as option to protect cable wrap if any)
Position			better 20 bit
• encoder resolution			< 5 arcsec
• resolution shaft			< 100 µrad
• repeatability (static)			> ±100
Rate (deg/sec)			> ±200 (50 kg payload; also J dependent)
Acceleration (deg/sec <sup>2</sup> )	[iIPSC-SINAX-50]	> ±40	(130 kg payload; also J dependent)
Acceleration (deg/sec <sup>2</sup> )	[iIPSC-SINAX-130]	> ±40	
Torque cont./peak (Nm)			30/60

### Environment

Operating Temperature	0 °C to +45 °C full operational (other on request) 0 °C to +55 °C storage (other on request)
Altitude	up to 4'000 m above sea level or tbd
Vibration, Shock, EMI, EMC	designed to MIL-STD810F

### Color

White	RAL 9010 (true white)
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### Motion Limiters

Adjustable End Stops	The system contains hard stops and software defined end stops
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### Mounting Feet and Leveling

Adjustable Feet	The system contains three adjustable mounting feet
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### Gyro Stabilization

Stabilization Performance	with iNAT-M200/SLN-STAB < 200 µrad rms (option)
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### True North Capability

True Heading Performance	dual-antenna setup or gyro compassing (option)
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### Command / Remote Control

via CAN or RS232/422 or Ethernet or/and joystick (see iMAR's iSCU interface)
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Pictures below: Joystick Operator Panel (left) and iNAT-M200/SLC-DA Gyro Stabilization Unit with dual-antenna support (right)

