

# iIPSC-ANTRAD-201D

## Dynamic Azimuth/Elevation Axes Antenna Stabilizer and Positioner

The [iIPSC-ANTRAD-201D](#) is part of a family of single axis and two-axes stabilizers for antennas being used on naval and surface vessels.

- Open frame design for easy implementation of customer's antennas (e.g. phased-array)
- Dual axes gyro stabilization
- high angular resolution
- high dynamic capability
- standard vehicle power supply
- standard or customized RF and NF slip rings
- size and sliprings scaleable to operator's needs
- control via CAN or Ethernet or RS232/422



unit), integrated GPS, integrated iSCU stabilization & control unit and algorithms for stabilization and pointing to moving or static targets (satellites, vehicles), capability for conical scan and RF signal feedback for improved pointing performance. As an option the unit also can be delivered with external vibration absorbers.

All signals are fed via robust connectors of type MIL-C-38999-III and TNC to the user.

The antenna is protected against the environment by a radom, which can be adapted by its transmission behavior to the antenna operating frequencies. The system is delivered with full integrated servo motor and electronics, stabilization gyro or IMU (inertial measurement

The system is also available as single-axis antenna stabilization for surface and naval vessels.

Standard designs as well as customized designs are provided.

### Technical Data iIPSC-ANTRAD-201D:

Angular Positioning Rate:	$\pm 300$ °/s
Angular Acceleration:	$> 300$ °/s <sup>2</sup>
Positioning Resolution:	$< 1$ arcsec
Linearity / Scale factor error:	$< 0.003$ %
Accuracy in Position:	$< 5$ arcsec; resolution $< 1$ arcsec
Size:	designed for integrated 60 cm satellite antenna dish; 770 mm diameter, 950 mm height or customer specific (depends on radom design)
Antenna Payload Weight:	15 kg or TBD (customer's antenna and amplifier electronics)
Angular freedom:	azimuth rotation angle unlimited, elevation $-15...+105$ ° or TBD
Slip Rings:	RF sliprings, coax, 6 ways (DC to 2.2 GHz, 50 Ohm, insertion loss 2.5 dB max (TBD)) NF / DC sliprings, 20 ways, 2 A / line
Interfaces:	Ethernet / CAN / RS232/422 for command and read-out of stabilization and control
Inertial sensors / IMS:	standard: iVRU-FC; option iOLFOG-S-D or iMGYR-SN or TBD option: georeferencing system of type iTraceRT-F200 or iNAV-FMS or iNAV-FJI as option to aid the IMS on surface vehicles
Odometer input:	
Connector:	MIL-C-38999-III, TNC
Temperature:	$-20...+56$ °C (operating) or TBD
Environment / MTBF/ MTTR:	IP66 at radom site / 30.000 hrs (estimated) / 10 minutes
Size, Weight:	approx. 35 kg (without payload)
Power:	24 V DC ; 500 W (max at full dynamics; at standard tracking $< 150$ W)

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